



# RESEARCH MEMORANDUM

INVESTIGATION OF THE LIFT, CENTER OF PRESSURE, AND  
DRAG OF A PROJECTILE AT A MACH NUMBER OF 8.6  
AND A REYNOLDS NUMBER OF 17 MILLION

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## SUMMARY

Models of a high-speed projectile configuration were tested in free flight to determine the lift-curve slope, center of pressure, and drag at Mach numbers near 8.6 and at a Reynolds number of 17 million. These results were compared with predictions based on available theory and experimental results. The drag of a similar cone model was also measured.

## INTRODUCTION

The aerodynamic consequences of improving the static longitudinal stability of a 5° half-angle cone by adding a short spike of heavy material onto the nose are considered in this paper. The resulting shape (see fig. 1) was enough different from a cone that some changes in aerodynamic properties were expected. The lift on the added cylinder was expected to increase the lift at angle of attack and to cancel some of the gain in stability by moving the center of pressure forward. It was also expected that there would be at least a small region of quasi two-dimensional flow just behind the spike which might alter the lift, center of pressure, and drag. The presence of the shock wave at the spike base was expected to promote boundary-layer transition. The net effects of these changes were of sufficient interest that the present experimental investigation was undertaken. Tests were made to determine lift, drag, and center of pressure of the projectile. The drag of unmodified cones was also measured for comparison.

Since the speeds of interest for this body were in the high supersonic Mach number range, the tests were run at the highest Mach number compatible with model strength considerations. The tests were made at speeds near  $M = 8.6$  in the Ames supersonic free-flight wind tunnel at a

Reynolds number of over 17 million, based on model length. In this facility the models are fired upstream through the test section of an  $M = 2.0$  supersonic wind tunnel to attain high relative airspeed.

## SYMBOLS

a	projection in the $x,z$ plane of the instantaneous acceleration of model center of gravity normal to the tunnel center line, $\text{ft/sec}^2$
$C_D$	drag coefficient, $\frac{D}{S\dot{q}_0}$
$C_{D_0}$	drag coefficient at $\alpha = 0$
$\bar{C}_{L_R}$	lift coefficient corresponding to mean vector sum of $\alpha$ and $\beta$ in test interval
$C_{L_\alpha}$	lift-curve slope, $\frac{dC_L}{d\alpha}$ , per radian
$C_m$	pitching-moment coefficient about model center of gravity, <u>pitching moment</u> $S\dot{q}_0$
$C_{m_\alpha}$	pitching-moment-curve slope, $\frac{dC_m}{d\alpha}$ , per radian
D	drag, lb
E,F	constants defining variation of $\alpha$ with time
e	base of Naperian logarithms
f	frequency of pitching motion, cps
I	principal moment of inertia about lateral axis through model center of gravity, $\text{ft-lb sec}^2$
k	damping constant, $\text{sec}^{-1}$
L	lift, lb
l	model length, ft
M	test Mach number
m	model mass, slugs

Q	double integral with respect to time of the angle-of-attack function, sec <sup>2</sup>
q <sub>0</sub>	free-stream dynamic pressure, lb/sq ft
R	Reynolds number based on model length and free-stream conditions
S	frontal area of model, sq ft
t	time, sec
w	projection in x-z plane of the instantaneous velocity of model center of gravity normal to tunnel center line, ft/sec
X <sub>cg</sub> , X <sub>cp</sub>	distance from model nose to center of gravity and center of pressure, respectively, ft
x,y,z	orthogonal coordinate system using tunnel center line as x axis, ft
$\alpha$	angle of attack of model relative to local flight path, radians
$\bar{\alpha}_R$	mean value of vector sum of $\alpha$ and $\beta$ during test interval, radians
$\beta$	angle of sideslip of model relative to local flight path, radians
$\omega$	$2\pi f$ , radians/sec

#### Subscripts

1,2,3,4 stations in wind tunnel

#### APPARATUS AND TECHNIQUES

##### Wind Tunnel

The tests were conducted in the Ames supersonic free-flight wind tunnel. This facility is a short ballistic range inside a variable-pressure, supersonic, blowdown wind tunnel. While the tunnel was operating at a Mach number of 2.0, the models were fired upstream through the 15-foot-long test section at 5600 feet per second from a gun located in the diffuser. The aerodynamic data were obtained from a history of the

model motion, as recorded by seven shadowgraph stations (four parallel to the  $x,z$  plane and three parallel to the  $x,y$  plane) and a chronograph. The data from the four-station group are used to study the motion of the models as if the model motion were confined to the  $x,z$  plane. Details of the data analysis and a discussion of measures taken to account for motion outside the  $x,z$  plane are included in the section entitled "Data Reduction." Details of tunnel operation are given in reference 1.

### Models

The models (fig. 1) were machined from 75 ST-6 aluminum bar stock. For the projectile the basic  $5^{\circ}$  half-angle cone was altered by adding a cylinder of one third the length, and of 0.19 the base diameter of the original cone. The cylinder and nose cone would presumably be made of heavy material in a full-size missile to promote stability. The models for the present tests were bored out at the base to provide the same effect. A conical hole with rounded bottom was bored in each projectile model to place the center of gravity at about the 71-percent point aft of the nose. This resulted in a wall thickness of about 0.035 inch, which permitted the model to be accelerated about 400,000 gravities in the gun without deformation. The nose cones were finished carefully and the bluntest one fired was 0.003 inch flat at the tip; most tips were less than 0.001 inch flat.

The surface finish was produced by a fine finishing cut and a little hand sanding in the lathe. No effort was made to improve the surfaces further and they were satin-like in appearance. Several model surfaces were examined in order to evaluate the equivalent roughness at large scale. A photograph of a typical model is given in figure 2, and photomicrographs of a model surface and profile are given in figure 3. The pictures are representative of the worst conditions noted; for example, the dip, which is indicated in the profile picture is 0.0001 inch deep by 0.0030 inch long. This profile is believed to be representative of the test models, but no extensive examination of model surfaces was made. The models were fired from a high performance .50 caliber gun and were held on the sabot by evacuating the space in the base of the model as indicated in figure 1. The high-pressure powder gases in the gun chamber penetrated the plastic-tape seal, and a small amount of gas flowed into the evacuated model. The resistance to acceleration held the model firmly in place until the sabot was free of the gun. At this moment the powder-gas pressure in the model forced separation from the sabot face.

## Data Reduction

The lift-curve slope, center of pressure, and drag were calculated from the record of model motion as a function of time. The component of the resultant aerodynamic force parallel to the  $z$  axis, that is, the lift, was obtained by measuring the acceleration along this direction; the center of pressure was found from the natural pitching frequency and the lift-curve slope; and the drag was determined by measuring the axial deceleration. Details of the lift and center-of-pressure calculations are presented below; the details of drag calculation, which is more readily visualized, are given in reference 1. For the purpose of data reduction, linear aerodynamic characteristics are assumed. The effect of nonlinearity is treated approximately.

As mentioned previously the data from the four shadowgraph stations recording the model motion in the  $x, z$  plane were used as if the model were free to move in this plane only. The instantaneous acceleration of the model projected on the  $x, z$  plane may be written

$$a = \frac{d^2 z}{dt^2} = \frac{C_L \alpha_{q0} S}{m} \quad (1)$$

which is Newton's law of motion in the  $x, z$  plane. This assumes a linear lift curve and neglects the contribution of the small lift force due to pitching and plunging.

The time variation of angle of attack in equation (1) can be obtained using the angle-of-attack measurements from the shadowgraph pictures and two assumptions which define the form of the motion. The assumptions are that the restoring moment and damping moments are proportional to the angle of attack and pitching rate, respectively. This leads to a variation of angle of attack given by

$$\alpha = e^{-kt} (E \cos \omega t - F \sin \omega t) \quad (2)$$

Equation (2) is fitted to the observed variation of  $\alpha$  with respect to time by a least-squares procedure described in reference 2. In this way the four unknowns,  $\omega$ ,  $k$ ,  $E$ , and  $F$ , are evaluated.

Combining equations (1) and (2) gives the plunging acceleration as a function of time

$$\frac{d^2 z}{dt^2} = \frac{dw}{dt} = \frac{C_L \alpha_{q0} S}{m} e^{-kt} (E \cos \omega t - F \sin \omega t) \quad (3)$$

Integrating with respect to  $t$  gives the following equation for vertical velocity,  $w$

$$w = \frac{dz}{dt} = w_1 + \frac{C_{L\alpha} q_0 S}{m} \int_{t_1}^t e^{-kt} (E \cos wt - F \sin wt) dt \quad (4)$$

in which  $w_1$  is the component of the model velocity along the  $z$  axis at the first station. A second integration gives the equation of vertical position relative to the initial point  $z_1$ . The integrals are evaluated between limits corresponding to the times and positions in two shadowgraph stations.

$$z_2 = z_1 + w_1 (t_2 - t_1) + \frac{C_{L\alpha} q_0 S}{m} \int_{t_1}^{t_2} \int_{t_1}^{t_2} e^{-kt} (E \cos wt - F \sin wt) dt dt \quad (5a)$$

The integral on the right can be evaluated since the integrand and limits are known. For brevity, it will be designated  $Q_{12}$ .

$$z_2 = z_1 + w_1 (t_2 - t_1) + \frac{C_{L\alpha} q_0 S}{m} Q_{12} \quad (5b)$$

In equation (5b) the unknowns are  $C_{L\alpha}$  and  $w_1$ ; the constant  $w_1$  is eliminated by using data from a third station:

$$z_3 = z_1 + w_1 (t_3 - t_1) + \frac{C_{L\alpha} q_0 S}{m} Q_{13} \quad (5c)$$

solving equations (5b) and (5c) simultaneously yields the following expression for  $C_{L\alpha}$ :

$$C_{L\alpha} = \frac{m}{S q_0} \frac{\frac{z_2 - z_1 - (z_3 - z_1)}{t_3 - t_1} \frac{t_2 - t_1}{t_3 - t_1}}{Q_{12} - Q_{13} \frac{t_2 - t_1}{t_3 - t_1}} \quad (6)$$

In order to determine the center-of-pressure position, it was also necessary to measure the pitching-moment-curve slope,  $C_{m\alpha}$ , for use in the equation relating lift- and moment-curve slopes:

$$\frac{x_{cg} - x_{cp}}{l} C_{L\alpha} = C_{m\alpha} \quad (7)$$

The value  $C_{m\alpha}$  was obtained from the frequency of oscillation as determined by the least-squares fit to the angle-of-attack history. The equation for the frequency of oscillation with one degree of freedom was used:

$$f = \frac{1}{2\pi} \omega = \frac{1}{2\pi} \sqrt{\frac{-C_{m\alpha} q_0 S l}{I}}$$

or

$$C_{m\alpha} = - \frac{\omega^2 I}{S q_0 l} \quad (8)$$

The method of calculation of lift requires data from three stations in the wind tunnel to determine one lift answer. For each of the tests from which lift-curve slope was obtained in this investigation, four shadowgraphs were made. This permitted making four combinations of three stations from each set. Occasionally, one combination of three stations failed to define the lift-curve slope because the position of the stations along the flight path was such as to record three values of  $z$  which fell nearly on a straight line. Such badly defined values are not included. Typical data from which lift and center-of-pressure location were determined are shown in figure 4.

Thus far the motion has been treated as an oscillation in the  $x, z$  plane. Actually, the models were free to move in the  $x, y$  plane as well. If the aerodynamic properties of the model were perfectly linear, there would be no influence on the data if this fact were ignored. Since it was expected, in this case, that the lift would be influenced by sideslip angle, the value of  $C_{L\alpha}$  was related to the mean absolute angle of yaw, the vector sum of  $\alpha$  and  $\beta$ , during the interval in question, rather than to  $\alpha$  alone. Thus,

$$\bar{C}_{L_R} = C_{L\alpha} \bar{\alpha}_R$$

where  $\bar{C}_{L_R}$  is called the lift coefficient corresponding to the mean absolute angle of yaw,  $C_{L\alpha}$  is the value of lift-curve slope obtained as described above, and  $\bar{\alpha}_R$  is the mean absolute angle of yaw for the test interval.

#### ACCURACY

A realistic estimate of the accuracy of the above techniques must of necessity be based on consistency of results, rather than on a detailed study of all factors contributing inaccuracies. The lift results are

consistent within a scatter in  $\bar{C}_{LR}$  of  $\pm 0.008$ , based on frontal area, for the present test. This amounts to less than  $\pm 4$  percent of the measured lift at  $5^\circ$  angle of attack. The drag is believed accurate within 2 percent. The total scatter in center-of-pressure position of six separate tests was  $\pm 1.2$  percent of the body length. The static stability margin of the models was made small, from 0.3 to 2.5 percent of  $l$ ; therefore the determination of center-of-pressure position was not sensitive even to large errors in  $C_{m\alpha}$ .

## RESULTS

The testing technique is such that varying amounts of disturbance are imparted to the models as they are launched. These differences, plus slight damage suffered by a few models, made it necessary to consider each test individually. Only the aerodynamic parameters best defined by each test have been included here as explained below.

### Lift

The variation of lift with angle of attack,  $\bar{C}_{LR}$  versus  $\bar{\alpha}_R$ , as deduced from four tests (1, 2, 3, and 5), is presented in figure 5. Out of a total of 16 lift-curve-slope determinations, 2 were deleted, 1 each from tests 2 and 5, because the data were such as to fail in defining the flight-path curvature accurately.

Test 1 had a peak amplitude of oscillation of about  $1^\circ$  and deviated about 0.07 inch from straight-line flight. Tests 2, 3, and 5 had larger amplitudes. The model in test 2 was bent about  $1.5^\circ$  at the base of the spike during the launch (see fig. 6(b)). The effect of this damage was estimated by calculating the theoretical lift on the conical spike nose (ref. 3) at  $1.5^\circ$  angle of attack and doubling this to allow for lift carry-over on the spike cylinder. This lift was then added in coefficient form to the values of  $\bar{C}_{LR}$  determined from this test and amounted to a correction of about 7 percent of the final answer. Test 3 had the largest amplitude recorded in the investigation - about  $10^\circ$ . The nose tip (about 1 percent of the model length) was hooked over by lateral acceleration in the gun. The hook was bent in a plane nearly normal to the  $x,z$  plane, so it is believed that this damage had negligible effect on the lift.

### Center of Pressure

Tests of five models (1, 5, 7, 8, and 9) showed the center of pressure to be between 72.1 and 74.6 percent of the length aft of the nose.

For all of these tests the oscillatory motion was fairly well defined and the models were not visibly damaged (see fig. 6).

### Drag

Five tests were obtained with accurate enough time-distance measurements for determining drag (1, 4, 5, 6, and 7). These results are plotted in figure 7 as a function of the average position of boundary-layer transition along the model as observed in the shadowgraphs. The drag due to lift of these models was estimated and subtracted as outlined in reference 1.

The principal evidences of turbulent boundary-layer flow are eddies visible in shadowgraphs and small waves sent out by these eddies. A region of turbulent flow may be seen near the base of the model in figure 6(j). This patch of turbulent flow is being swept downstream at about half the free-stream velocity as evidenced by the angle of the weak shock wave emanating from it. Scrutiny of all the pictures from a test permitted the estimation of transition position. In the case of test 6 no laminar flow was seen aft of the spike cylinder. It is believed that transition did, in fact, occur at the nose due to some slight damage not visible in the shadowgraphs. In view of the difficulty of seeing boundary-layer turbulence near the nose, the point for this test is plotted as if transition occurred at the spike base.

The drag tests of two unmodified cones are also reported in this figure. The lower Reynolds number of these two tests resulted from using shorter models and testing at slightly lower tunnel pressure for testing convenience.

### DISCUSSION

The initial lift-curve slope predicted using reference 3 is indicated in figure 5 and is seen to underestimate the lift appreciably at angles of attack greater than  $3^{\circ}$ . A somewhat better model of the flow at angle of attack is given by impact theory (ref. 4) which predicts increasing lift-curve slope with increasing angle of attack. This predicted variation is plotted in figure 5; there is still a large gap between experiment and theory.

The nonlinearities indicated in impact theory may be evaluated differently using the crossflow concept proposed in reference 5 and further developed in reference 6. If the crossflow contribution is added to the continuation of the initial lift-curve-slope line of figure 5, the sum agrees quite well with the experiment. This crossflow-lift increment was

calculated on the basis of 70 percent of the supercritical drag coefficient of a circular cylinder being developed on an expanding body at angles of attack above  $2.5^\circ$ . This value, 70 percent, was chosen on the basis of results given in reference 6 for the nose of an ogive cylinder. The agreement, perhaps better than might reasonably be expected, still indicates the possibility of accurate lift calculation by presently available methods.

The effect of the spike on the lift appears to be small. Its frontal area, less than 4 percent of the model base area, would indicate that even if the lift carry-over from the nose were equal to the nose lift, the total lift would be increased by only 4 percent. The spike apparently did not affect the lift on the main body to any great degree, as was indicated by the success in calculating the total lift.

The center-of-pressure position was estimated theoretically, ignoring the lift developed by the spike cylinder and assuming that the pressures on the aftercone were not affected by the presence of the cylinder. The resulting center of pressure, essentially the center of plan-form area of the conical portions, is predicted to be 74.2 percent of  $l$  aft of the nose. The median experimental value of 73.3 percent agrees well with this prediction. If the lift carry-over from the nose cone onto the cylinder is assumed equal to the nose-cone lift and acts at one third the cylinder length aft of the nose cone, the predicted location is 73.4 percent  $l$  aft of the nose. It is expected that at large angles of attack, the center of pressure moves forward slightly since the spike-cylinder lift variation is expected to be more nonlinear than that for the conical portions.

The estimates of the zero-lift drag of the projectile were based on references 4, 7, and 8 for wave drag and reference 9 for skin friction. The base pressure was assumed to be 10 percent of free-stream static pressure, based on extrapolation of the data of reference 10. The wave drag estimated by use of reference 4 was about 20 percent below that predicted by use of reference 7 for a  $5^\circ$  cone. The value from reference 7 only is presented in figure 7.

The theoretical drag build-up for both configurations is presented in figure 7. The skin friction was calculated using local conditions and the effect of heat transfer was included. The data of reference 9, and subsequent data, as yet unpublished, obtained by the same technique, were used in these calculations.

The effect of heat transfer was to increase the skin friction by some 35 percent over that which would have existed without heat flow, according to reference 9. In order to see if the wall to free-stream temperature ratio was the same as for the tests of reference 9, estimates were made of the maximum temperature rise the model could have experienced. Before firing, the model temperature was around  $540^\circ R$  and the free-stream static temperature was  $300^\circ R$ . At  $M = 8.6$  the recovery temperature was

around  $4300^{\circ}$  R, and the flight duration was 0.008 second. At the outset, it is useful to note that even if the entire model surface were to be raised to the melting point,  $1420^{\circ}$  R, the temperature difference causing heat transfer would be reduced by only 23 percent. That this extreme temperature rise did not, in fact, occur is evidenced by the perfect condition of models observed at the last shadowgraph station.

Calculations of the maximum possible temperature rise of the model based on the appendix of reference 11 indicated a temperature rise on the spike cylinder, just behind the nose cone, of  $30^{\circ}$  R and  $1000^{\circ}$  R at the apex. Thus the temperature rise on 97 percent of the wetted area was less than  $30^{\circ}$  R and the maximum temperature rise at the nose, as indicated by its survival, was less than  $880^{\circ}$  R. Thus it is seen that the wall to stream temperature relation of the skin-friction tests also applies to the present test.

Two calculations of the local Mach number and dynamic pressure, on which the skin-friction calculations were based, were made. The first was based on reference 7 and ignored the effect of the spike on the flow over the main body. The second was based on reference 7 for the nose cone, and shock-expansion theory, reference 8, for the remainder of the body. The pressure distributions and skin-friction results from these two calculations were nearly identical, indicating no important effect of the cylinder on the pressure distribution on the remainder of the body at small incidence.

As is indicated in figure 7, boundary-layer transition generally occurred well downstream of the spike base. In many cases the flow was laminar over the entire body length, but it never remained so throughout an entire flight. Thus it appears that at the present test conditions of high Mach number and large heat-transfer rate into the model surface, a laminar boundary layer is extremely stable.

#### CONCLUDING REMARKS

Presently available theories may be used for engineering estimates of lift, center-of-pressure location, and wave drag of the projectile and the drag of the  $5^{\circ}$  half-apex-angle cone from which the projectile shape was derived. The lift for the projectile at angles of attack around  $3^{\circ}$  and above is noticeably greater than predicted by linear theory.

A good estimate of friction drag was made on the basis of presently available data which include the effect of heat transfer.

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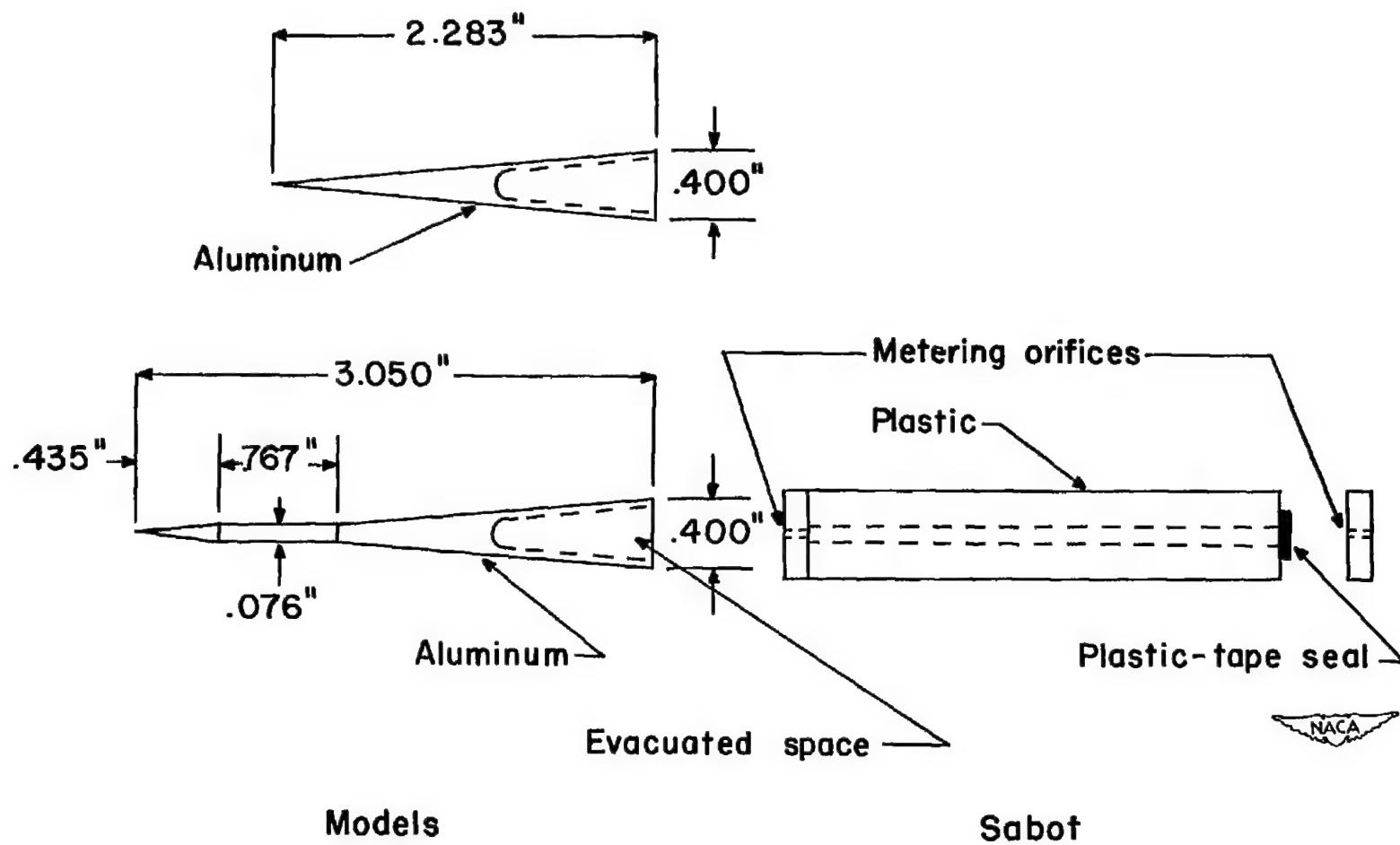


Figure 1.- Models and sabot.

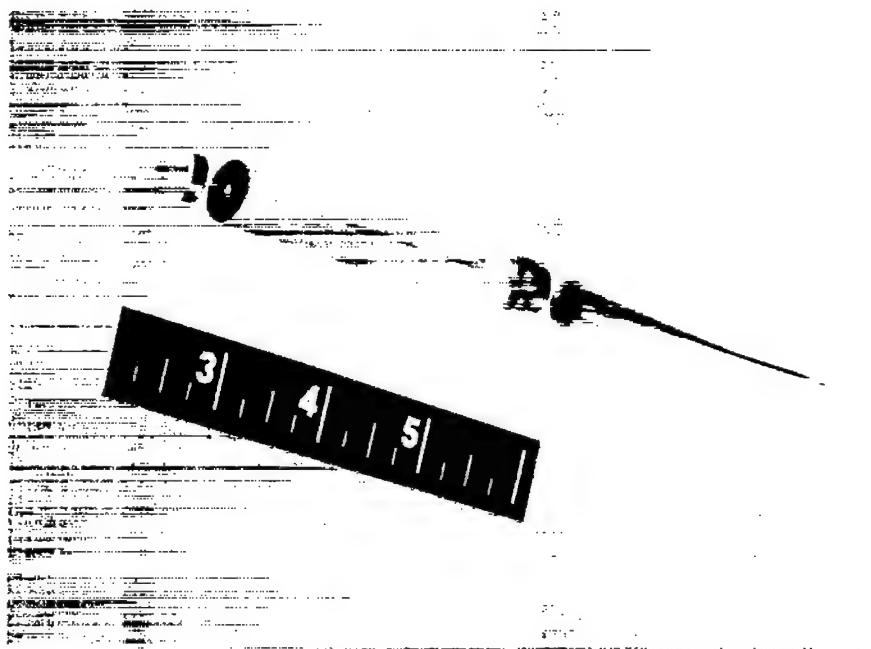
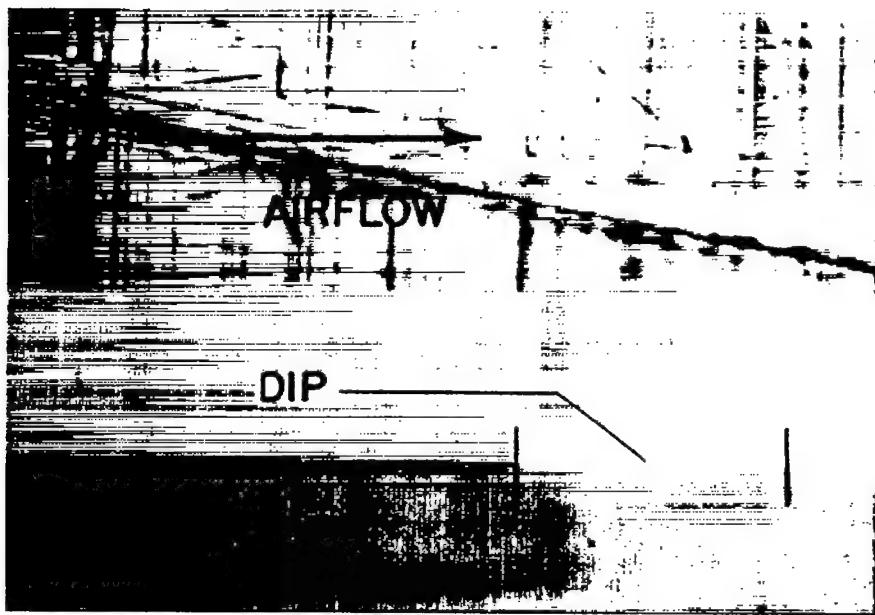
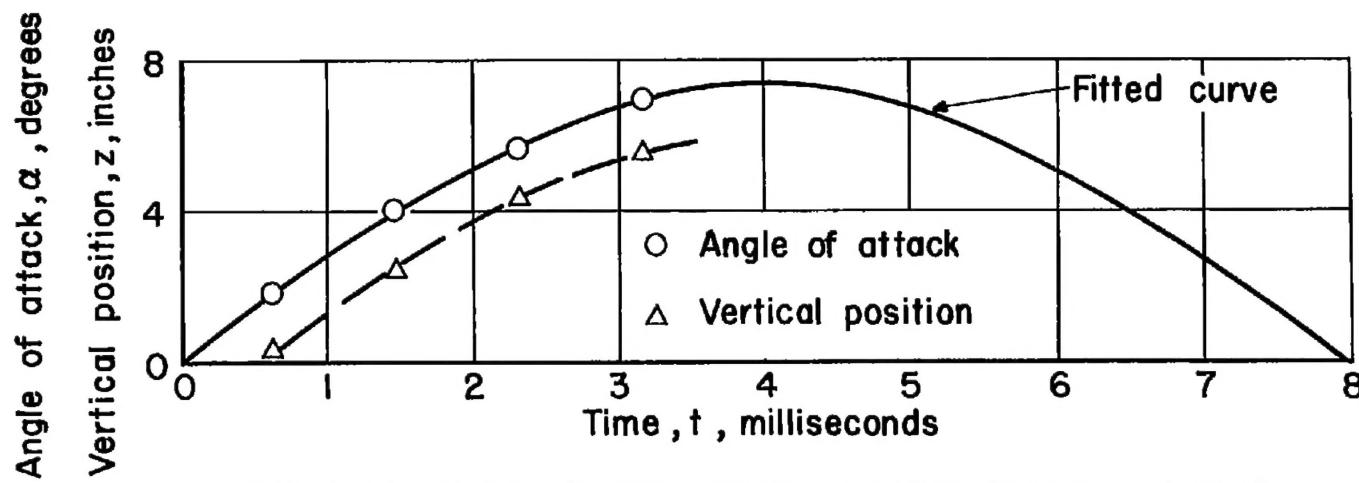


Figure 2.- Expanded assembly of model and sabot.

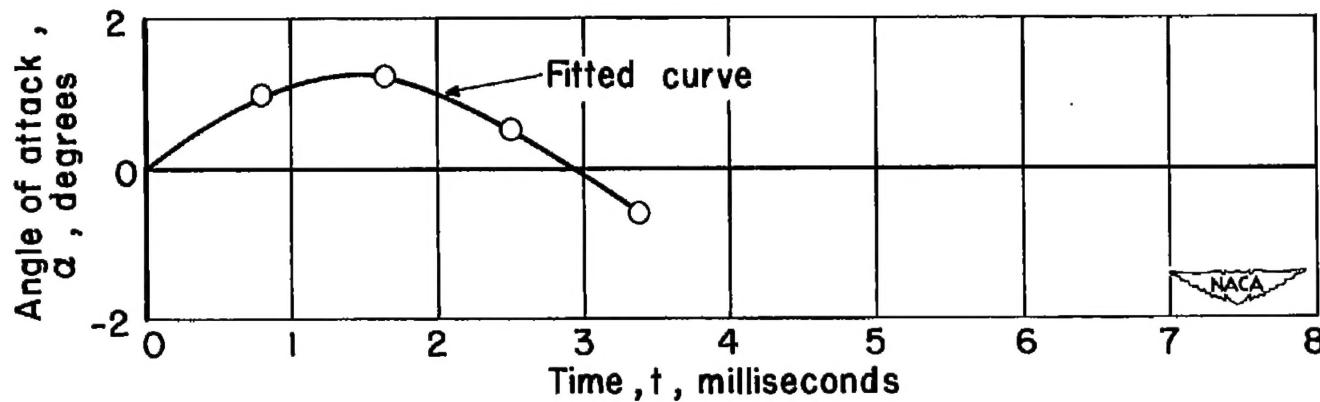


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Figure 3.- Photomicrographs of model surface and profile, X400.



(a) Angle-of-attack and vertical-position histories , test 3.



(b) Angle-of-attack history , test 1.

Figure 4.- Plots of basic data for two tests.

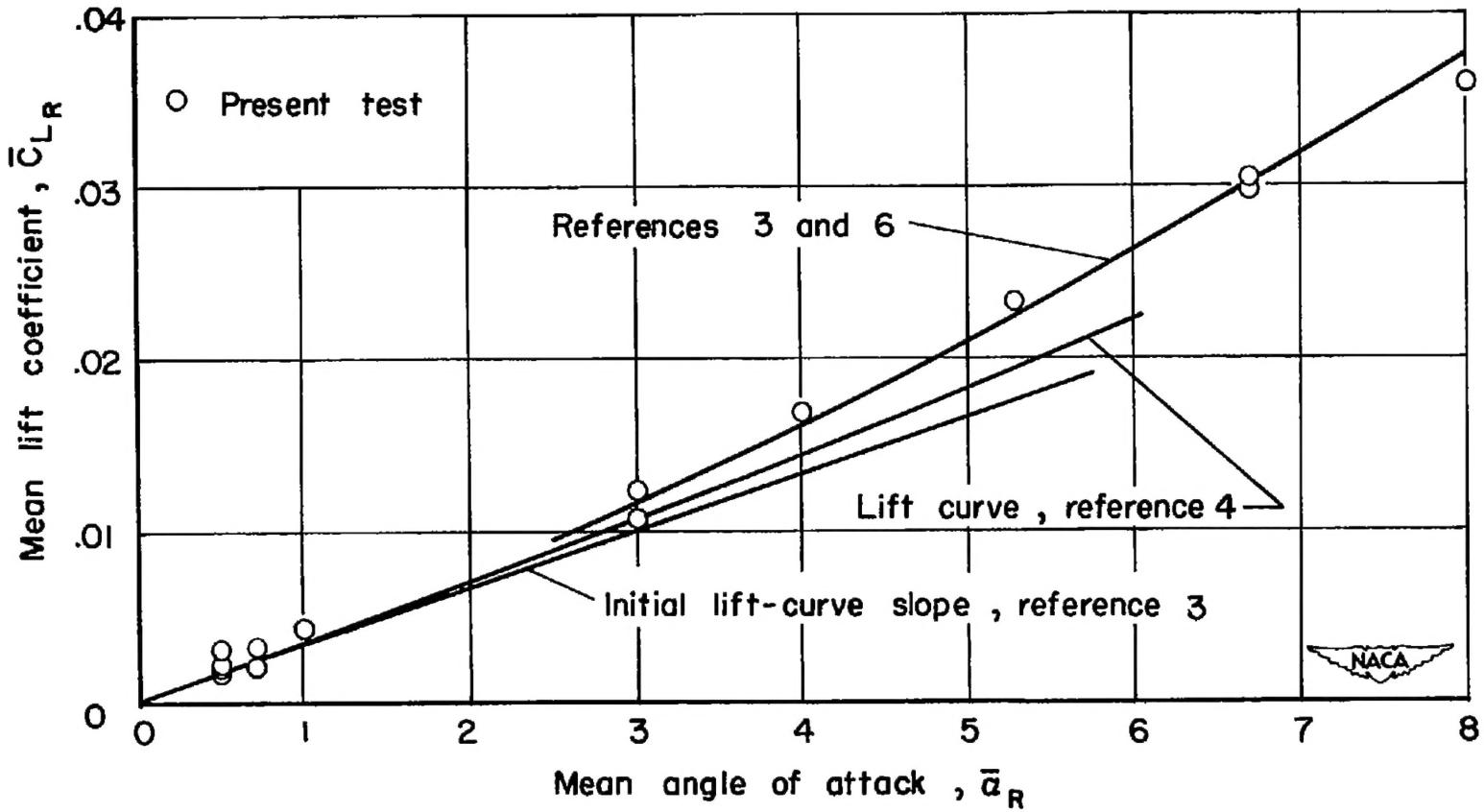


Figure 5 . - Variation of mean lift coefficient with mean angle of attack.



(a) Test 1, station 2



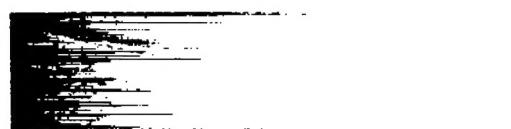
(f) Test 6, station 3



(b) Test 2, station 1



(g) Test 7, station 4



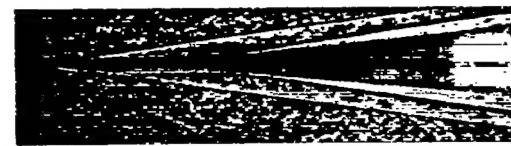
(c) Test 3, station 4



(h) Test 8, station 2



(d) Test 4, station 1



(i) Test 9, station 3



(e) Test 5, station 2



(j) Test 10, station 1



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(k) Test 11, station 1

Figure 6.- Shadowgraphs of models in flight.

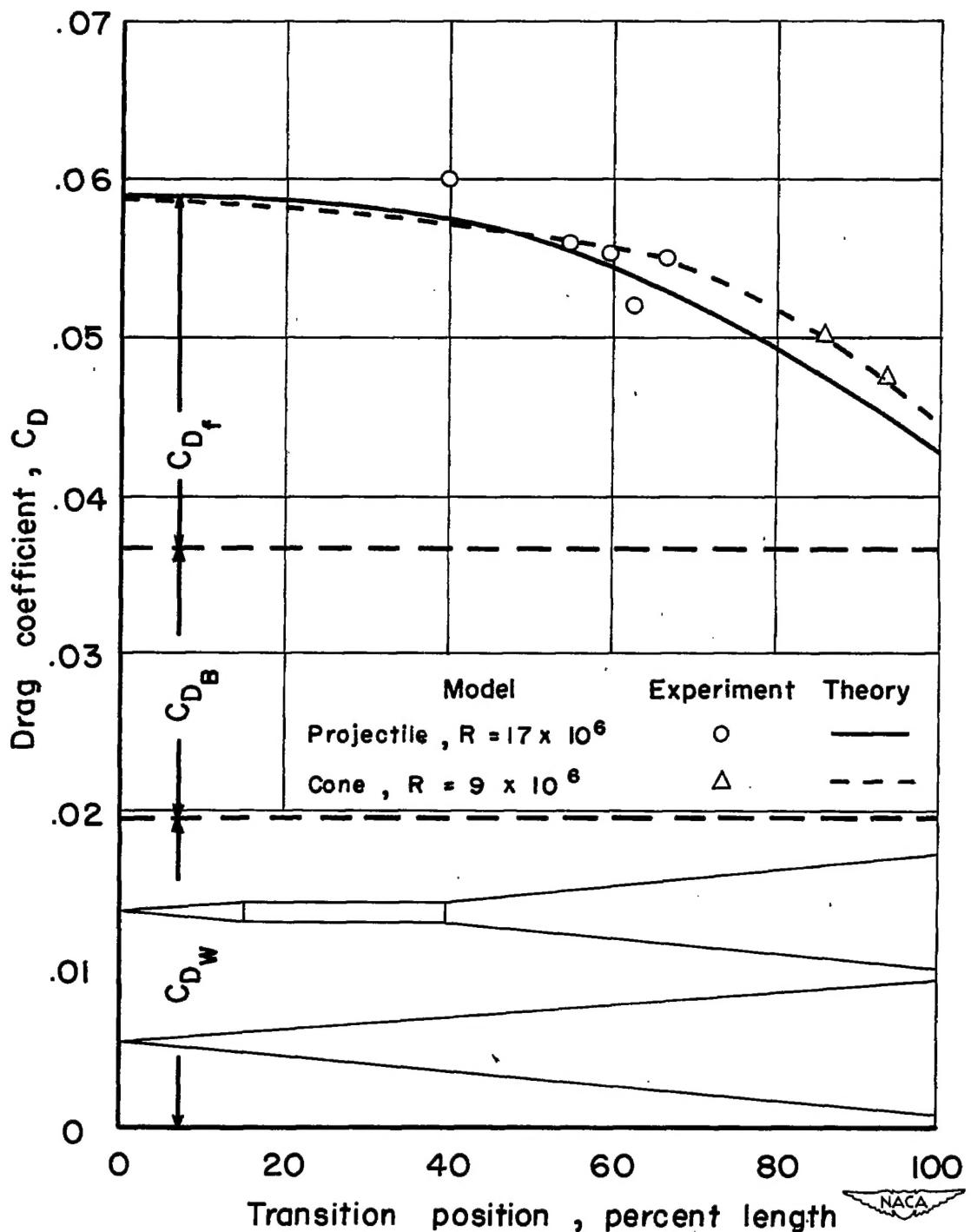


Figure 7.- Variation of drag of projectile and a  $5^\circ$  cone with position of transition location.  $M \approx 8.6$ .